



Adaptive Control: Stability, Convergence, and Robustness (Prentice-Hall Advanced Reference Series)

Shankar Sastry

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With a focus on linear, continuous time, single-input, single-output systems, this volume surveys the major results and techniques of analysis in the field of adaptive control. The authors offer a clear, conceptual presentation of adaptive methods, enabling a critical evaluation of these techniques and suggesting avenues of further development.

A brief historical overview of adaptive control is followed by a review of mathematical preliminaries and the development of several adaptive identification algorithms. Succeeding chapters examine averaging techniques, the robustness of adaptive schemes, and advanced topics — including the use of prior information and multivariable adaptive control — followed by a concise introduction to the control of a class of nonlinear systems. The treatment is largely self-contained, assuming only some graduate-level background in basic control systems and in linear systems theory.

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